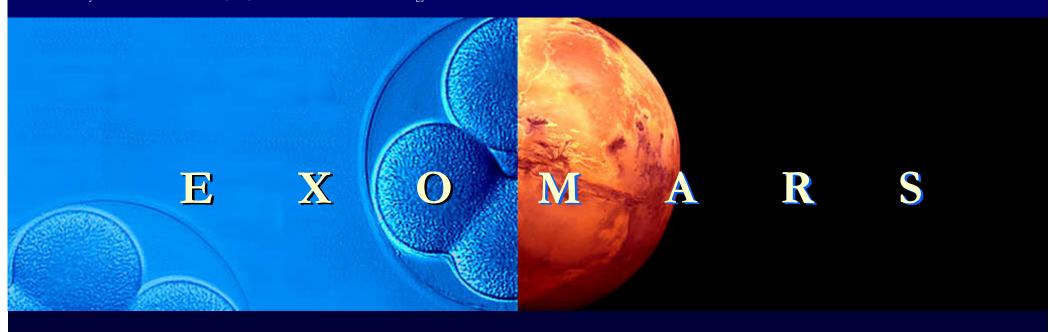
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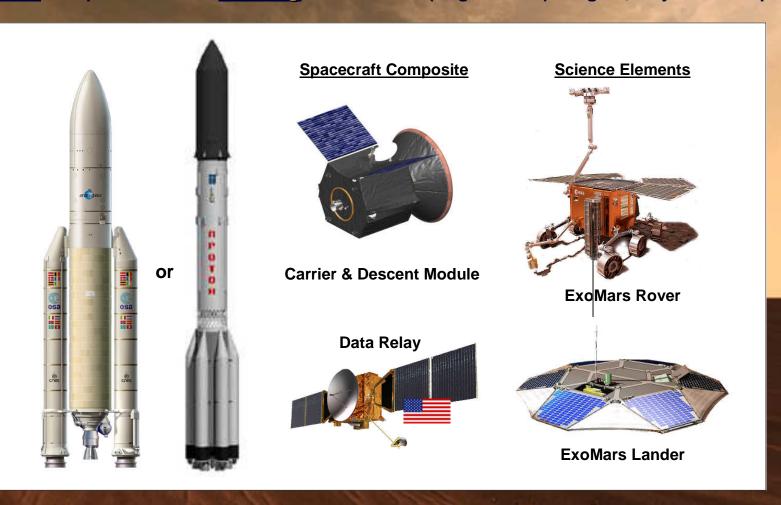




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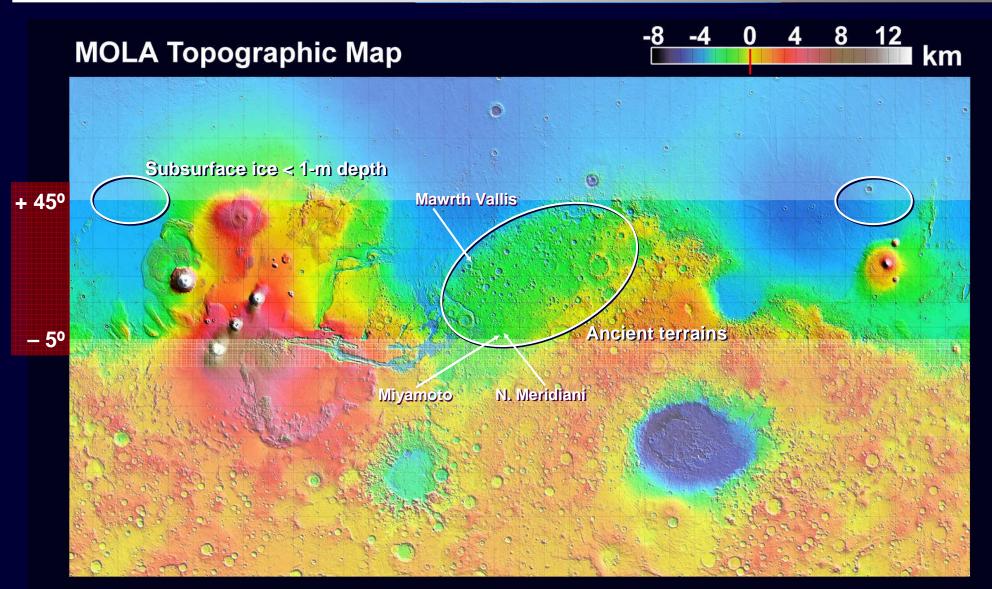
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Landing Sites



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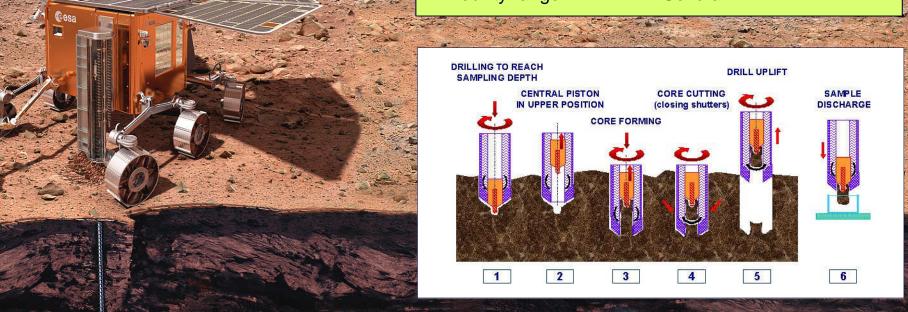
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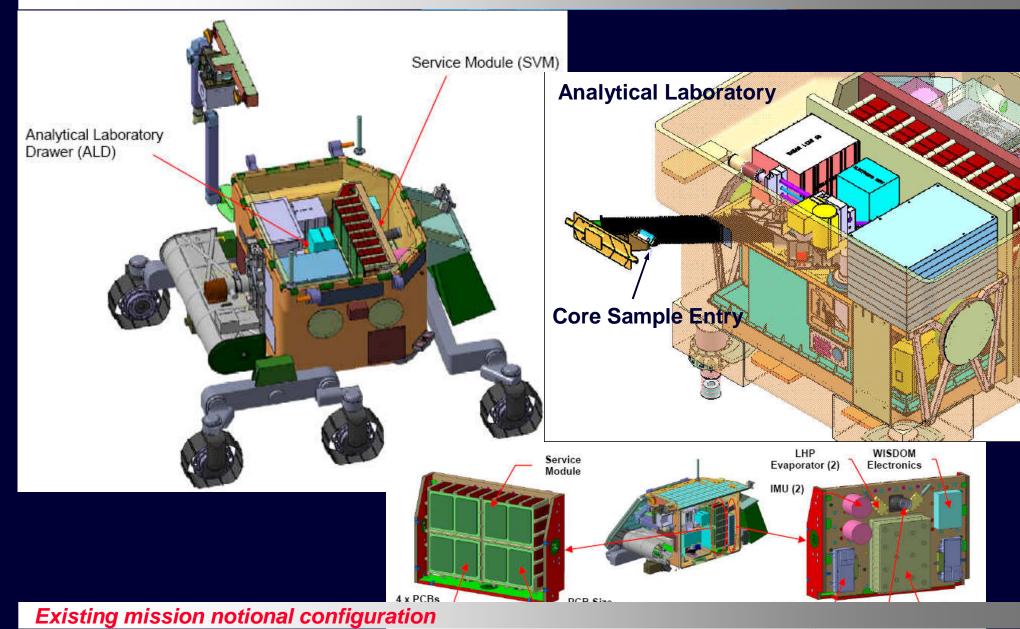
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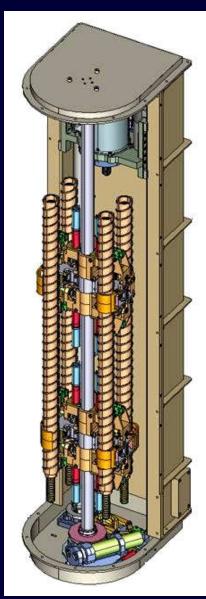


Rover Internal Architecture





Drill System











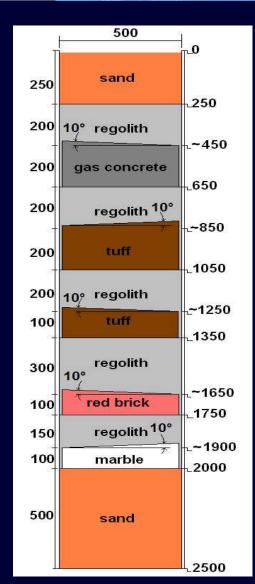


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2 m depth drilling, ambient conditions

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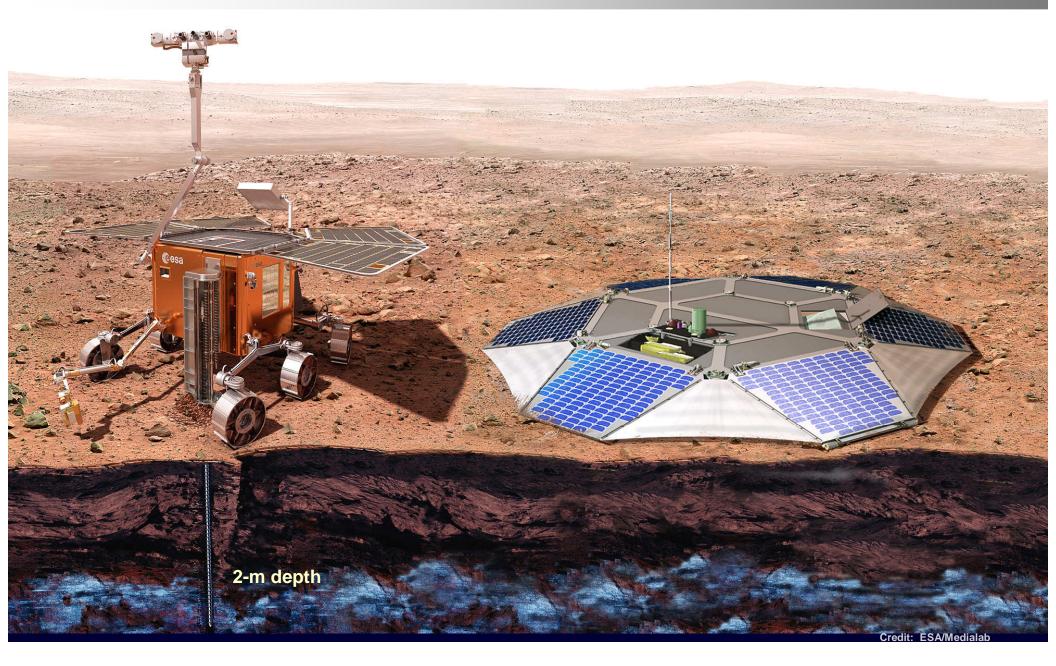
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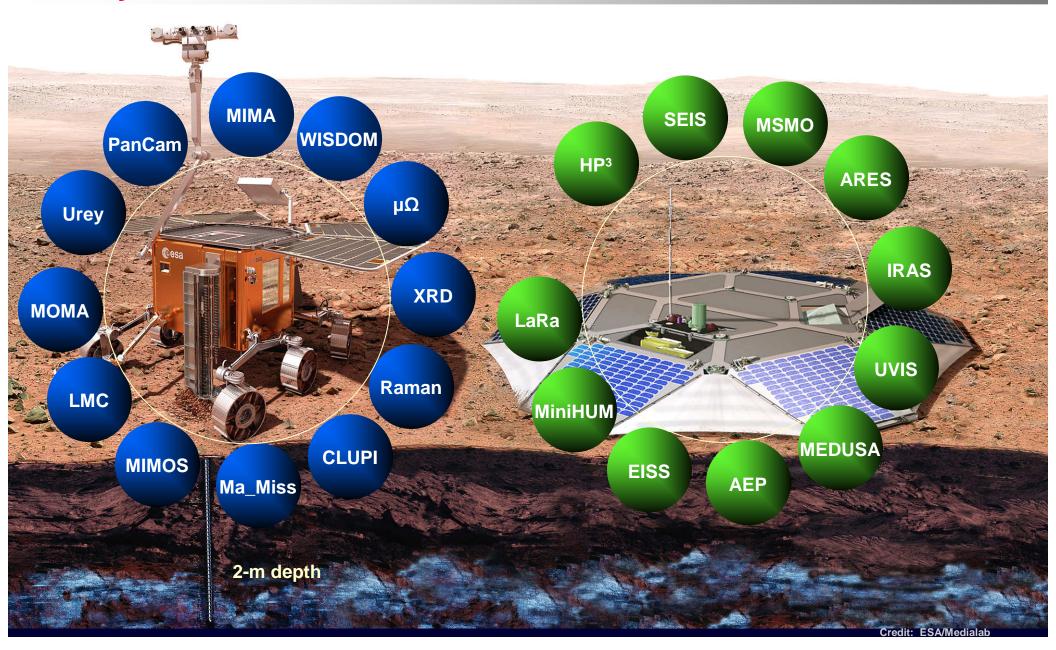


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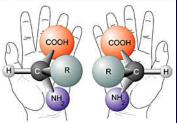
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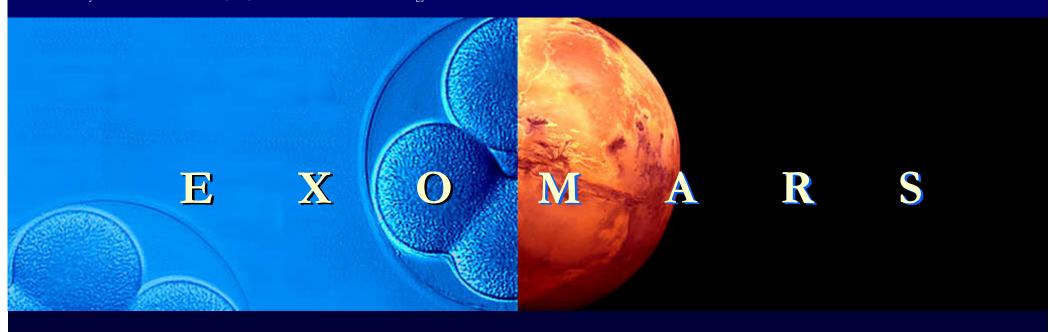
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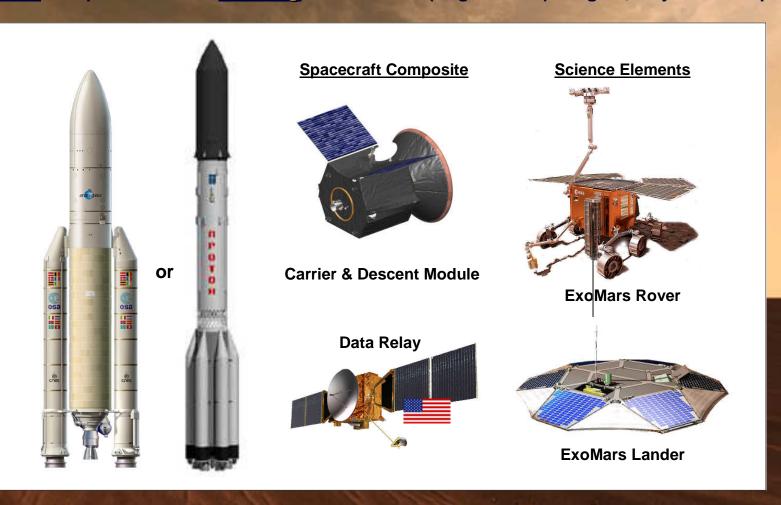




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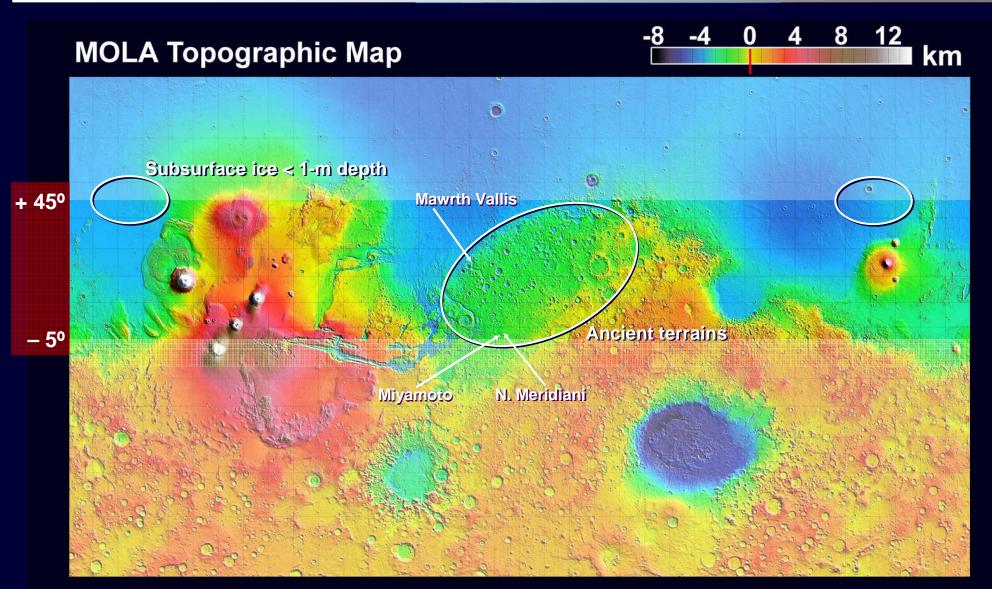
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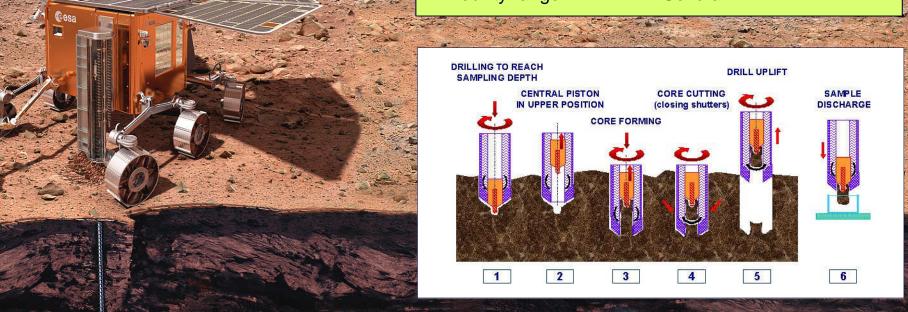
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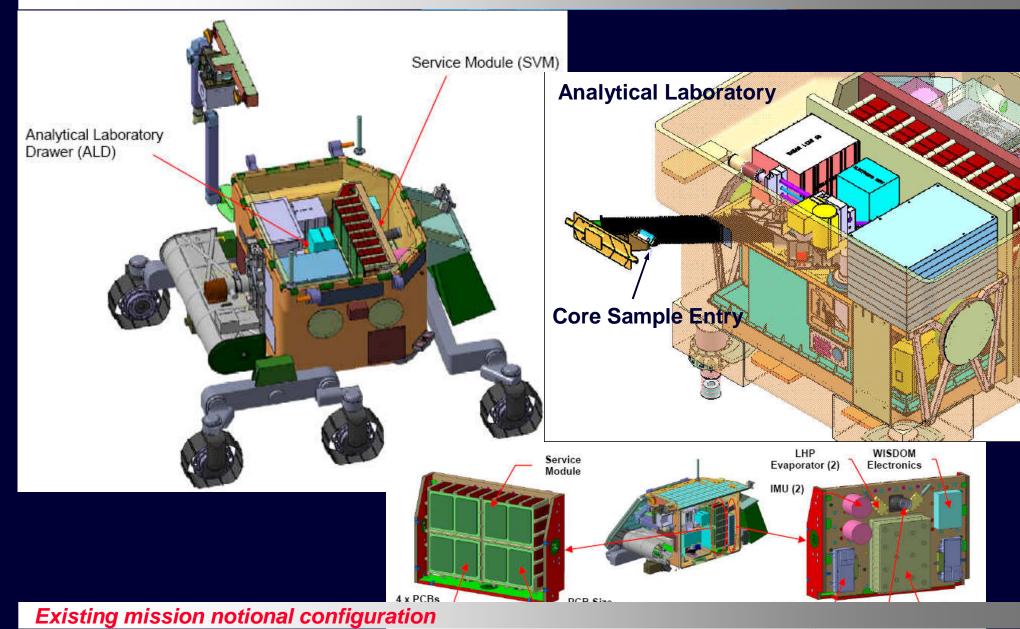
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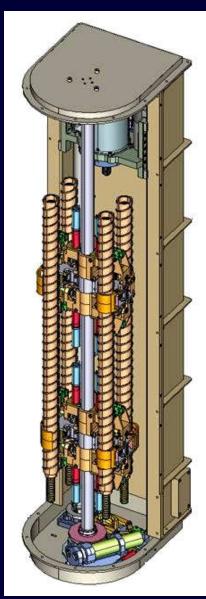


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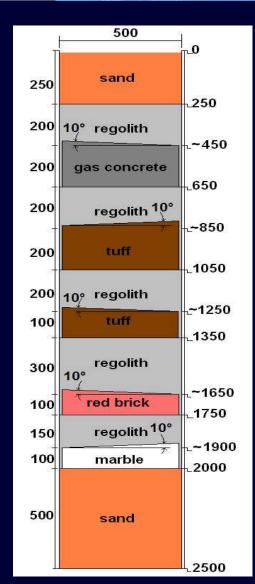


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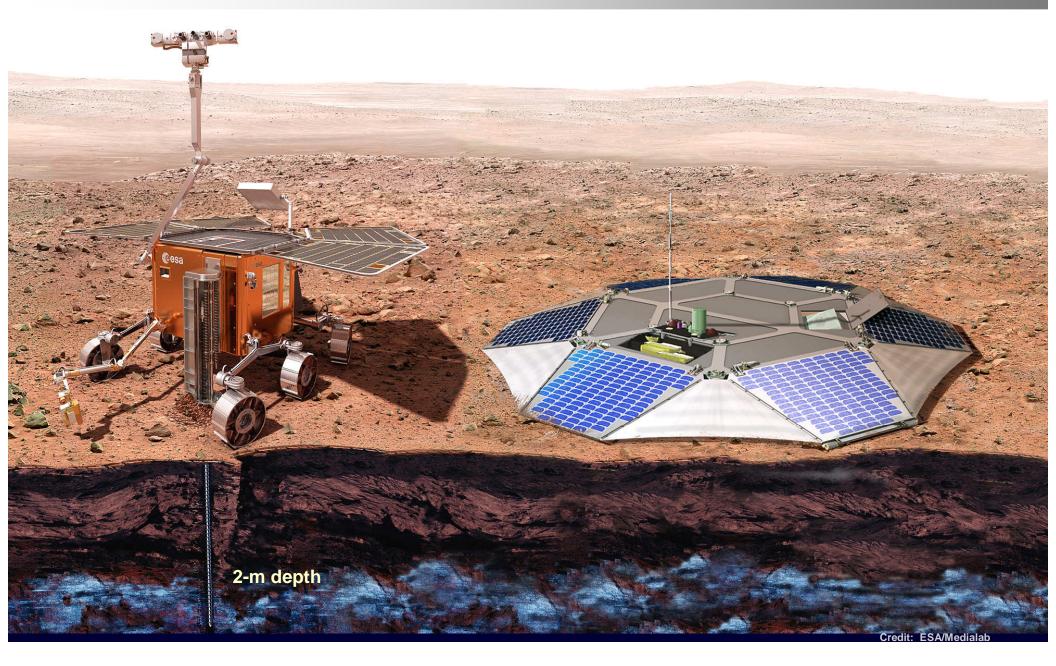
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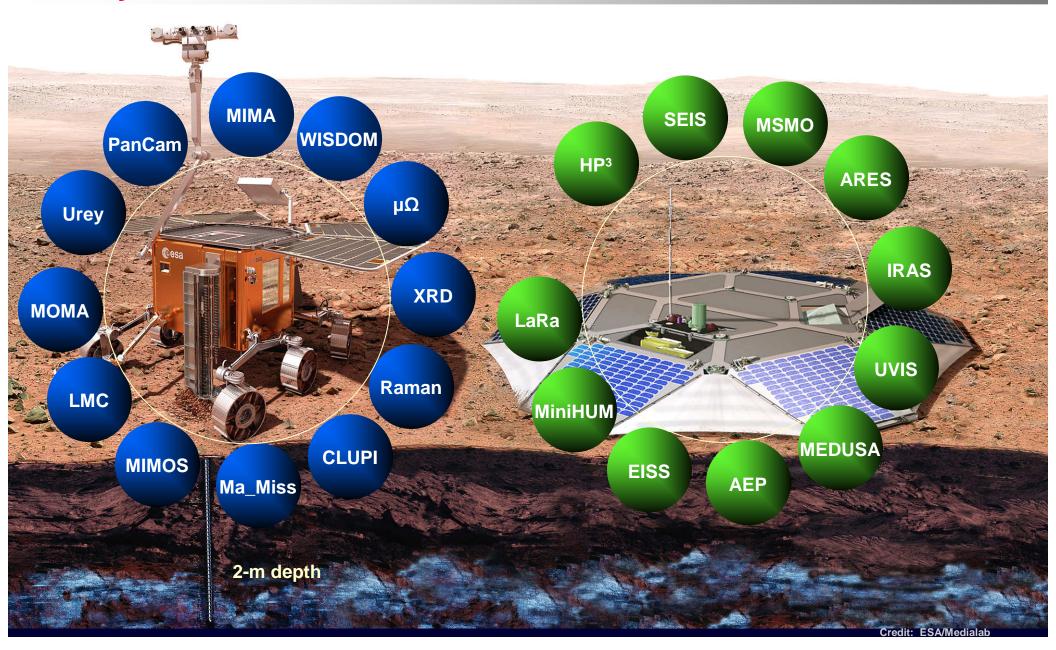


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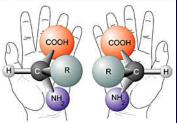
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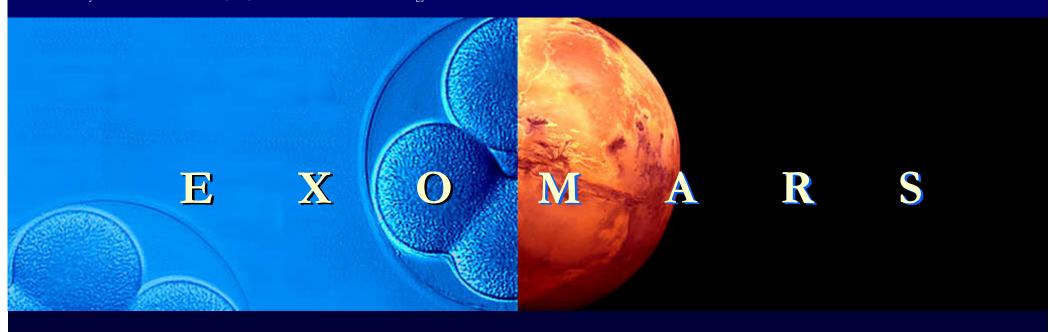
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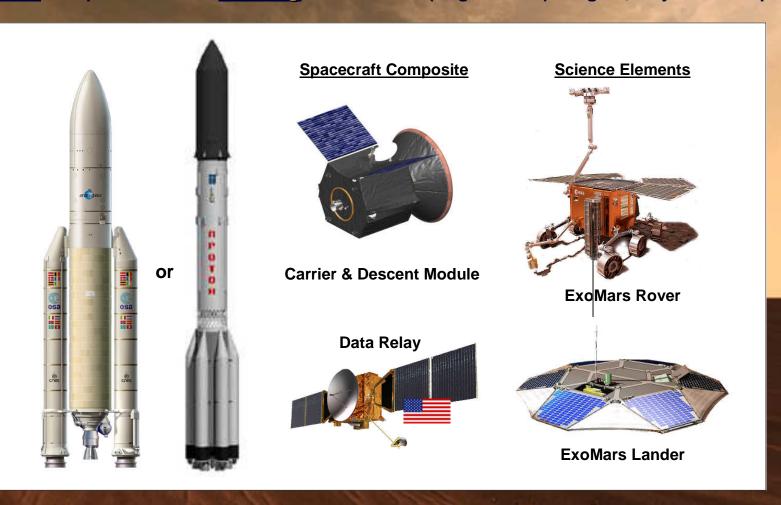




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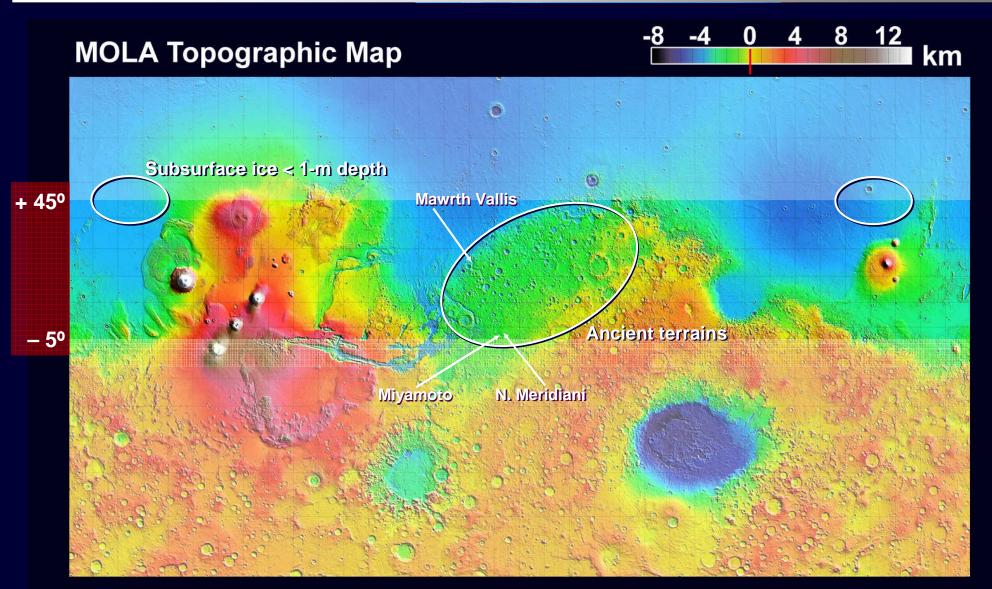
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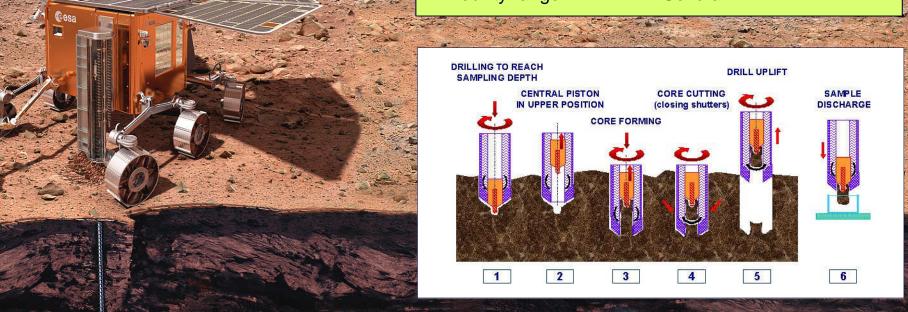
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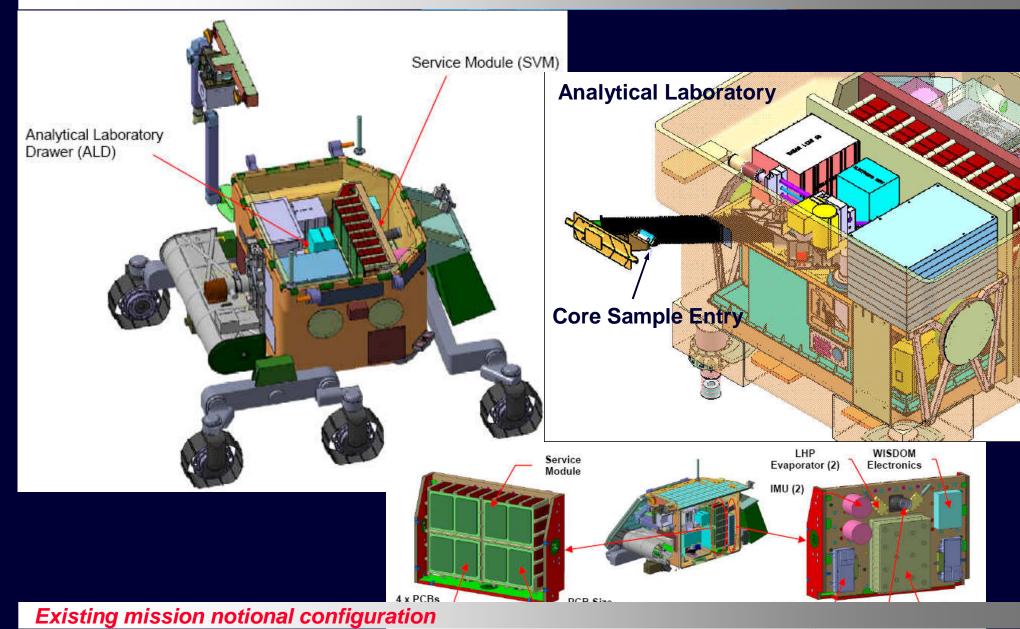
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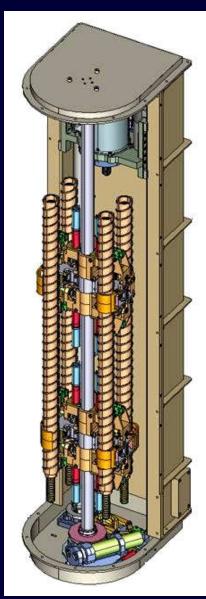


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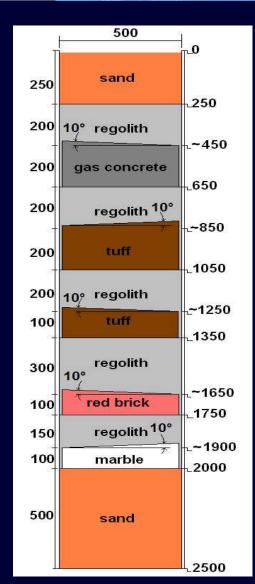


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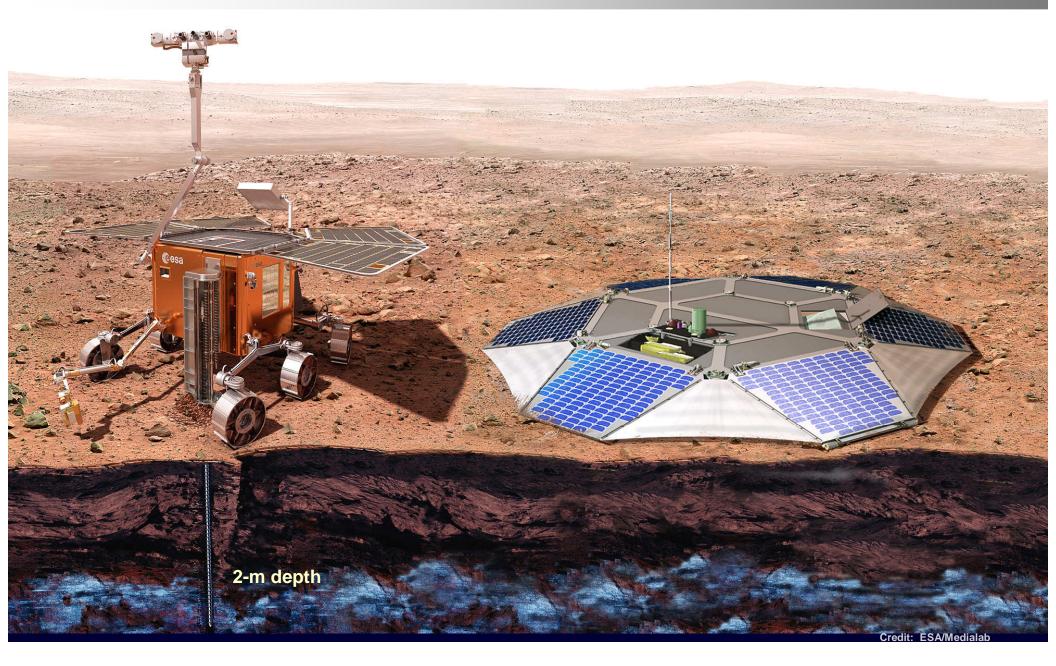
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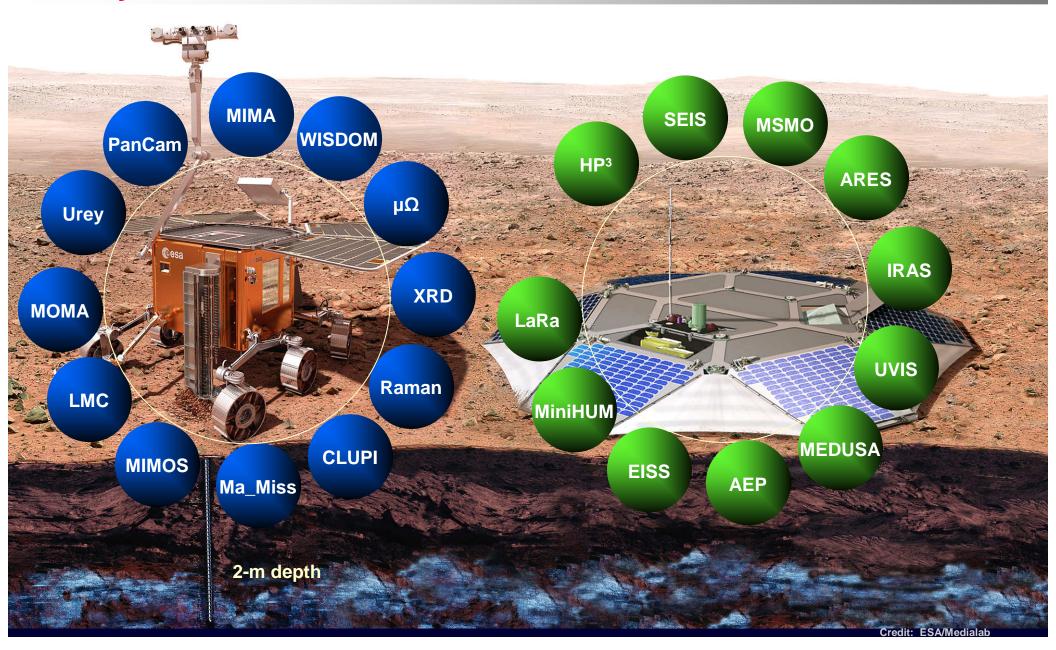


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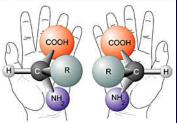
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